

OPERATING INSTRUCTIONS E12S REV. 0

Variable Reluctance Speed Sensor

GREEN LINE

INDUSTRIAL SPEED SENSORS

Product ID

E12S

	Type #	Product #	Drawing #		
	E12S	385Z-05226	113.296 Rev.2		
General					
Function	The E12S series variable reluctance (VR) speed sensors consist of an iron core an inductive coil, and a permanent magnet. A ferrous pole wheel passing the sensor face changes the magnetic field strength, resulting in an AC voltage being induced in the coil. The frequency of the output signal is proportional to th speed of the moving target. The amplitude of the signal depends on speed, air gap, geometry of target, magnetic properties of target material, and the electrica load. VR sensors, also known as passive or electromagnetic sensors, do not require an external supply.				
Technical data					
Coil properties	Resistance: 85	r: north pole towards front fac	е		
Polarity	Upon approach of	ferrous metal, the signal pin	is positive with respect to GND.		
Signal output	The signal frequency is proportional to the target speed. The signal amplitude shown in the figure is valid for a load of 100 kOhm, and is affected by air gap, target geometry and material. It is also proportional to the linear speed of the teeth.				
	Typical output voltage (reference speed 10 m/s, 100 kOhm load)				
	Beak Amplitude (X)		M = 0.5 M = 1.0 M = 2.0 M = 4.0		
	0.10 0.5	1 1.5 2 Air gap (mm)	2.5 3 3.5 4		
Frequency range	Up to 20 kHz, lower limit depending on application				
Housing	M12x1, tightening torque: max. 12 Nm				
Connection	Cable with open leads: 3-wire, 3 x 0.34 mm2 (AWG22), stranded wires, elastomer isolation, green casing, fire retardant, low smoke, RoHS conform and halogen free, max. outer & = 4.8 mm, min. bending radius = 25 mm (static) and 50 mm (dynamic), cable length according to dimensional drawing				
Protection	Sensor head: IP68 Cable outlet: IP67				
Insulation	Housing and electronics galvanically isolated (Test: 500 V, 50 Hz for 1 minute)				
Pole wheel	Prerequisite: Toothed wheel of a ferrous material (e.g. Steel 1.0036). Optimal performance with Involute gear Tooth width > 10 mm				



IN CHARGE OF SPEED

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	Side offset < 0.2 mm Eccentricity < 0.2 mm	
Air gap between sensor and pole wheel	Depending on lowest circumferential speed which has to be detected and on trigger level. See figure.	
Electromagnetic compatibility (EMC)	Please contact Jaquet for further details.	
Vibration & shock immunity	Jaquet Greenline sensors are approved for rough environments. Please contact Jaquet for further details.	
Operating temperature	-40°C125°C	
Further Information		
Safety	All mechanical installations must be carried out by an expert. General safety requirements have to be met.	
Installation	The sensor has to be aligned to the pole wheel according to the sensor drawing independent of its rotational orientation. Deviations in positioning may affect the performance and decrease the noise immunity of the sensor. During installation, the smallest possible pole wheel to sensor gap should be set. The gap should however be set to prevent the face of the sensor ever touching the pole wheel. A sensor should be mounted with the middle of the face side over the middle of the pole wheel. Dependent upon the wheel width, a certain degree of axial movement is permissible. However, the middle of the sensor must be at minimum in a distance of 3 mm from the edge of the pole wheel under all operating conditions. A solid and vibration free mounting of the sensor is important. Eventual sensor vibration relative to the pole wheel can induce additional output pulses. The sensors are insensitive to oil, grease etc. and can be installed in arduous conditions.	
Maintenance	Product cannot be repaired.	
Transport	Product must be handled with care to prevent damage of the front face.	
Storage	Product must be stored in dry conditions. The storage temperature corresponds to the operation temperature.	
Disposal	Product must be disposed of properly, it must not be disposed as domestic waste.	



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